

**LIST OF PATENTS AND PUBLICATIONS FOR APPLICANTS'  
INFORMATION DISCLOSURE STATEMENT**

INFORMATION DISCLOSURE STATEMENT BY APPLICANT		Application Number	10/718,913
		Filing Date	November 21, 2003
		Inventor	McBean et al
		Art Unit	3772
		Examiner	Brown, Michael
		Atty Docket	1118/A04

Non-Patent References		
Examiner's Initials	Ref. No.	Document Number, Publication Date, Inventor
	BQ	Lum, et al., "A Robotic System for Upper-Limb Exercises to Promote Recovery of Motor Function Following Stroke", ICORR '99: International Conference on Rehabilitation Robotics, Stanford, CA, pages 235-239
	BR	Lum, et al., "Quantification of Force Abnormalities During Passive and Active-Assisted Upper-Limb Reaching Movements in Post-Stroke Hemiparesis", 1999, IEEE Trans on Biomed, Vol 46, No 6, pages 652-662
	BS	Lum, et al., "Robotic Assist Devices for Bimanual Physical Therapy Preliminary Experiments", 1993, IEEE Transactions on Rehabilitation Engineering, Vol. 1, No. 3, pages 185-191
	BT	Parsons, et al., "An Adaptable User Interface and Controller for a Rehabilitation Robotoc Arm, 1997, ICAR, pages 919-923
	BU	Popovic, et al., "Hybrid Assistance System-The Motor Neuroprosthesis", 1989, IEEE Transactions on Biomedical Engineering, Vol. 36, No. 7, pages 729-737
	BV	Rabischong, et al., "Control and Command of a Six Degrees of Freedom Active Electrical Orthosis for Paraplegic Patient", 1990, IEEE International Workshop on Intelligent Robots and Systems, pages 987-991
	BW	Reinkensmeyer, et al., "Guidance-Based Quantification of Arm Impairment Following Brain Injury: A Pilot Study", 1999, IEEE Transactions on Rehabilitation Engineering, Vol 7, No. 1, pages 1-11
	BX	Romilly, et al., "A Functional Task Analysis and Motion Stimulation for the Development of a Powered Upper-Limb Orthosis", 1994, IEEE Transactions on Rehabilitation Engineering, Vol. 2, No 3, pages 119-129

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	BY	Timoszyk, et al., "Robot-Assisted Locomotion Training after Spinal Cord Injury – Comparison of Rodent Stepping in Virtual and Physical Treadmill Environments", Department of Mechanical and Aerospace Engineering and Center for Biomedical Engineering, University of California, Irvine, 1990 IEEE International Conference, pages 1-14
	BZ	Triolo, et al., "The Theoretical Development of a Multichannel Time-Series Myoprocessor for Simultaneous Limb Function Detection and Muscle Force Estimation", 1989, IEEE Transactions on Biomedical Engineering, Vol. 36, No. 10, pages 1004-1017
	CA	Wu, et al., "A Study of Neuromuscular-like Control in Rehabilitation Robot", Proceedings of the 1996 IEEE International Conference on Rotobics and Automation, Minneapolis, MN, 0-7803-2988-4/96, April 1996, pages 1178-1183
	CB	Zardoshti-Kermani, et al., "EMG Feature Evaluation for Movement Control of Upper Extremity Prostheses", 1995, IEEE Transactions on Rehabilitation Engineering, Vol. 3, No. 4, pages 324-333

Examiner Signature: \_\_\_\_\_

Date Considered: \_\_\_\_\_

EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 609; draw a line through the citation if not in conformance and not considered. Include copy of this form with next communication to applicant.

**Identification of Person Making This Information Disclosure Statement**

The person making this statement is the practitioner who signs below on the basis of the information supplied by the inventor and in the practitioner's file.

Respectfully submitted,

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DATE: November 7, 2007

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